

**ASSIGNMENT 13: INVERSION OF THE RADON TRANSFORM  
(CONT.)**

Let's recall that in  $2d$  the Radon transform  $\mathcal{R}f$  can be inverted to obtain the function  $f$  by means of the filtered back projection

$$f = \mathcal{R}^* \circ (\mathcal{GR})f, \quad (1)$$

where  $\mathcal{GR}$  is the 'Filter' operator and the adjoint  $\mathcal{R}^*$  is the back projection operator. We have also shown that the Filter operator  $\mathcal{GR}$  is the Hilbert transform of the derivative of  $\mathcal{R}f$ , thus, the equation (1) can be written as

$$f = \mathcal{R}^* \circ \mathcal{H}(\partial_t \mathcal{R})f. \quad (2)$$

Alternatively, we have shown that using the fractional powers of the laplacian, i.e.,  $(-\Delta)^s$ , we can compute the inverse Radon transform of  $f$  as follows

$$f = \frac{1}{4\pi} (-\Delta)^{1/2} (\mathcal{R}^* \mathcal{R}f). \quad (3)$$

In the last assignment we considered the  $3d$  version of the Radon transform and, in particular, have shown that the Filter operator can be represented by a second partial derivative (in the affine coordinate) of the Radon transform ( $\mathcal{GR} = -\partial_t^2 \mathcal{R}f$ ), and hence, the reconstruction in the  $3d$  case, similar to the  $2d$  inversion formula (2) is

$$f = \mathcal{R}^* (-\partial_t^2 \mathcal{R}f), \quad (4)$$

or,

$$f(\vec{x}) = \mathcal{R}^* (-\partial_t^2 \mathcal{R}f)(\vec{x}), \quad \vec{x} \in \mathbb{R}^3.$$

In this assignment we will obtain an alternative inversion formula in  $3d$  which is analogous to (3). In fact, such an alternative formula can be obtained for all dimensions, see a remark afterwards.

**Problem 1.** Prove

$$f = \frac{1}{8\pi^2} (-\Delta)(\mathcal{R}^* \mathcal{R}f).$$

This equation is written in a way to resemble the one in (3).

(You may solve it however you want, one possibility is to follow the steps on the opposite page.)

**Remark.** The alternative inversion formula for the Radon Transform on  $\mathbb{R}^d$  is

$$f = \frac{1}{2(2\pi)^{d-1}} (-\Delta)^{(d-1)/2} (\mathcal{R}^* \mathcal{R}f),$$

where  $(-\Delta)^s$  is defined as  $(\vec{x}, \vec{\xi} \in \mathbb{R}^d)$

$$\widehat{(-\Delta)^s f(\vec{\xi})} = |\vec{\xi}|^{2s} \hat{f}(\vec{\xi}), \quad \text{or} \quad (-\Delta)^s f(\vec{x}) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} |\vec{\xi}|^{2s} \hat{f}(\vec{\xi}) e^{i\langle \vec{x}, \vec{\xi} \rangle} d\vec{\xi}.$$

## Solution Sketch

- a. Show, using the Central Slice Theorem and the definition of  $\mathcal{R}^*$ , that

$$\mathcal{R}^*\mathcal{R}f(\vec{x}) = \int_{S^2} \int_{-\infty}^{\infty} \hat{f}(r\vec{\omega}) e^{2\pi i r \vec{x} \cdot \vec{\omega}} dr d\sigma(\vec{\omega}).$$

- b. Plug the identity above into the formula  $\frac{1}{8\pi^2} (-\Delta)(\mathcal{R}^*\mathcal{R}f)$ .
- c. Take the Laplace operator  $(-\Delta)$  inside the integration (Justify it using one of the results from the notes on properties of the Lebesgue integral). Then, evaluate the operator, which is really a sum of partial derivatives, directly.
- d. Rewrite the integral, using the property of the Radon Transform that it is even, then multiplying by an appropriate constant and taking the integral in the affine parameter from 0 to  $\infty$ .
- e. Now evaluate the integral to get the result.