

# MAT 473 Intermediate Real Analysis II

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## Implicit functions

Given a system of  $m$  independent linear equations in  $n$  variables  $x_1, \dots, x_n$ , linear algebra tells us that we can solve for  $m$  of the variables in terms of the others. More precisely, if  $A$  is the coefficient matrix, then we can solve uniquely for  $x_{j_1}, \dots, x_{j_m}$  if and only if the columns  $j_1, \dots, j_m$  of  $A$  are linearly independent. For example, if  $A = \begin{pmatrix} B & C \end{pmatrix}$  is the block matrix decomposition with  $C$  square (of size  $m \times m$ ), and if  $C$  is invertible, then for any  $c \in \mathbb{R}^m$  the equation  $Bx + Cy = c$  can be solved uniquely for  $y$  as a function of  $x$ , namely  $y = C^{-1}(c - Bx)$ .

In the case of a nonlinear system of equations, the situation is similar, and is controlled by the derivative. To see what solving for  $y$  in terms of  $x$  entails, let  $f$  be a function from a subset of  $\mathbb{R}^n$  into  $\mathbb{R}^m$ , with  $m < n$  (the case  $m = n$  is handled by the Inverse Function Theorem). Put  $k = n - m$ , and identify  $\mathbb{R}^n$  with  $\mathbb{R}^k \times \mathbb{R}^m$ , so that a typical element is regarded as an ordered pair  $(x, y)$  with  $x \in \mathbb{R}^k$  and  $y \in \mathbb{R}^m$ . We want to solve an equation of the form  $f(x, y) = c$  for  $y$  in terms of  $x$ . In general, the best we can hope for is to solve for  $y$  in terms of  $x$  locally, so that near any sufficiently nice point in the domain of  $f$ , the set of solutions of  $f(x, y) = c$  should be the graph  $\{(x, g(x)) : x \in \text{dom } g\}$  of a function  $g$ .

Here is the main result:

**Theorem 1** (Implicit Function Theorem). *Let  $E \subset \mathbb{R}^n = \mathbb{R}^k \times \mathbb{R}^m$ , let  $f : E \rightarrow \mathbb{R}^m$  be  $C^1$ , and let  $(a, b) \in E$ . Write  $f'(a, b) = \begin{pmatrix} A & B \end{pmatrix}$  where  $B$  is  $m \times m$ , and assume that  $B$  is invertible. Put  $f(a, b) = c$ . Then there exist open sets  $U \subset E$  and  $W \subset \mathbb{R}^k$  such that  $(a, b) \in U$  and  $U \cap f^{-1}(c)$  is the graph of a  $C^1$  function  $g : W \rightarrow \mathbb{R}^m$ .*

Note that, once we have proved the above theorem, if we wanted to we could find open sets  $W_0 \subset W$  and  $V_0 \subset \mathbb{R}^m$  such that: (1)  $W_0 \times V_0 \subset U$ , (2) for all  $x \in W_0$  there exists a unique  $y = g_0(x) \in V_0$  such that  $f(x, y) = c$ , and (3) the resulting function  $g_0 : W_0 \rightarrow V_0$  is  $C^1$ . This is how the Implicit Function Theorem is sometimes phrased.

*Proof.* Define  $\phi : E \rightarrow \mathbb{R}^n$  by  $\phi(x, y) = (x, f(x, y))$ . Then  $\phi$  is  $C^1$ , and

$$\phi'(a, b) = \begin{pmatrix} I & 0 \\ A & B \end{pmatrix}$$

is invertible. By the Inverse Function Theorem there exist open sets  $U \subset E$  and  $V \subset \mathbb{R}^n$  such that  $(a, b) \in U$ ,  $\phi$  maps  $U$  1-1 onto  $V$ , and  $\phi^{-1} : V \rightarrow U$  is  $C^1$ .

Put

$$W = \{x \in \mathbb{R}^k : (x, c) \in V\}.$$

Then  $a \in W$ , and  $W$  is open because  $V$  is. Define  $g : W \rightarrow \mathbb{R}^m$  by

$$g(x) = \pi_2 \circ \phi^{-1}(x, c),$$

where  $\pi_2 : \mathbb{R}^n = \mathbb{R}^k \times \mathbb{R}^m \rightarrow \mathbb{R}^m$  is the projection onto the second coordinate (i.e.,  $\pi_2(x, y) = y$ ). Then  $g$  is  $C^1$  since  $\phi^{-1}$  is (and  $\pi_2$  is linear). By construction, for all  $(x, y) \in U$  we have both

$$x \in W \quad \text{and} \quad y = g(x)$$

if and only if  $(x, y) = \phi^{-1}(x, c)$ , equivalently  $f(x, y) = c$ . Thus  $U \cap f^{-1}(c)$  is the graph of  $g$ .  $\square$

In the above statement of the Implicit Function Theorem, there is nothing magical about our choice of the identification of  $\mathbb{R}^n$  with  $\mathbb{R}^k \times \mathbb{R}^m$ , namely with the “ $\mathbb{R}^k$ -variable” being  $(x_1, \dots, x_k)$ :

**Corollary 2.** *Let  $E \subset \mathbb{R}^n$ ,  $f : E \rightarrow \mathbb{R}^m$ , and  $a \in E$ . Assume that  $f$  is  $C^1$ . If columns  $j_1, \dots, j_m$  of  $f'(a)$  are linearly independent, then we can solve the equation  $f(x) = c$  for  $x_{j_1}, \dots, x_{j_m}$  as a  $C^1$ -function of the remaining variables.*

*Proof.* Just compose  $f$  with a rearrangement of coordinates and apply the Implicit Function Theorem.  $\square$

The Implicit Function Theorem allows us to solve  $f(x, y) = c$  as  $y = g(x)$  for a  $C^1$ -function  $g$ . The following result shows how to compute  $g'$  in terms of  $f'$ :

**Proposition 3.** *With the notation of the Implicit Function Theorem,*

$$g'(a) = -B^{-1}A.$$

*Proof.* Define  $h : W \rightarrow E$  by  $h(x) = (x, g(x))$ . Then  $h$  is differentiable, and

$$h'(a) = \begin{pmatrix} I \\ g'(a) \end{pmatrix}.$$

Since  $f \circ h$  is constant, we have

$$\begin{aligned} 0 &= (f \circ h)'(a) \\ &= f'(h(a))h'(a) \\ &= f'(a, b) \begin{pmatrix} I \\ g'(a) \end{pmatrix} \\ &= (A \ B) \begin{pmatrix} I \\ g'(a) \end{pmatrix} \\ &= A + Bg'(a), \end{aligned}$$

and the result follows by solving for  $g'(a)$ .  $\square$

The main idea of the above proof can be expressed loosely as follows: differentiating both sides of the equation  $f(x, g(x)) = c$  with respect to  $x$  gives

$$\frac{\partial f}{\partial x}(x, g(x)) + \frac{\partial f}{\partial y}(x, g(x))g'(x) = 0,$$

and we can solve for  $g'(x)$ . This can't be quite right, though, because we haven't bothered to define partial derivatives with respect to a “chunk” of variables. This could be put on a firm footing, but I didn't think it was worth it.

**Example 4.** Consider the system

$$\begin{aligned} u^5 + xv^2 - y + w &= 0 \\ v^5 + yu^2 - x + w &= 0 \\ w^4 + y^5 - x^4 &= 1 \end{aligned}$$

of 3 equations in the 5 real variables  $x, y, u, v, w$ .

Define  $f : \mathbb{R}^5 \rightarrow \mathbb{R}^3$  by

$$f(x, y, u, v, w) = (u^5 + xv^2 - y + w, v^5 + yu^2 - x + w, w^4 + y^5 - x^4).$$

Then  $f$  is  $C^1$ , and

$$f'(x, y, u, v, w) = \begin{pmatrix} v^2 & -1 & 5u^4 & 2xv & 1 \\ -1 & u^2 & 2yu & 5v^4 & 1 \\ -4x^3 & 5y^4 & 0 & 0 & 4w^3 \end{pmatrix}.$$

We have

$$f(1, 1, 1, 1, -1) = (0, 0, 1),$$

and

$$f'(1, 1, 1, 1, -1) = \begin{pmatrix} 1 & -1 & 5 & 2 & 1 \\ -1 & 1 & 2 & 5 & 1 \\ -4 & 5 & 0 & 0 & -4 \end{pmatrix}.$$

Since the matrix

$$\begin{pmatrix} 5 & 2 & 1 \\ 2 & 5 & 1 \\ 0 & 0 & -4 \end{pmatrix}$$

is invertible, we can apply the Implicit Function Theorem to conclude that there exist  $r > 0$  and  $C^1$ -functions  $h, k, l : B_r(1, 1) \rightarrow \mathbb{R}$  such that

$$h(1, 1) = 1, \quad k(1, 1) = 1, \quad l(1, 1) = -1,$$

and

$$\begin{aligned} h(x, y)^5 + xk(x, y)^2 - y + l(x, y) &= 0 \\ k(x, y)^5 + yh(x, y)^2 - x + l(x, y) &= 0 \\ l(x, y)^4 + y^5 - x^4 &= 1 \quad \text{for all } (x, y) \in B_r(1, 1). \end{aligned}$$

Moreover, we have

$$-\begin{pmatrix} 5 & 2 & 1 \\ 2 & 5 & 1 \\ 0 & 0 & -4 \end{pmatrix}^{-1} \begin{pmatrix} 1 & -1 \\ -1 & 1 \\ -4 & 5 \end{pmatrix} = \begin{pmatrix} -4/21 & 13/84 \\ 10/21 & -43/84 \\ -1 & 5/4 \end{pmatrix},$$

so

$$\begin{aligned} \frac{\partial u}{\partial x}(1, 1) &= \frac{-4}{21} & \frac{\partial u}{\partial y}(1, 1) &= \frac{13}{84} \\ \frac{\partial v}{\partial x}(1, 1) &= \frac{10}{21} & \frac{\partial v}{\partial y}(1, 1) &= \frac{-43}{84} \\ \frac{\partial w}{\partial x}(1, 1) &= -1 & \frac{\partial w}{\partial y}(1, 1) &= \frac{5}{4}. \end{aligned}$$